# THE FOUR FINGERS LIP

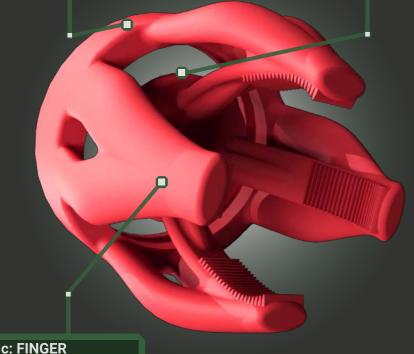
BUILD #1: a1.b1.c1

a: MATERIAL

1: STANDARD HARD

b: KERNEL

1: HOLLOW



# **ATTRIBUTES**

POWER 8
AGILITY 9

COMPLIANCE 6

# **DESCRIPTION**

This gripper lip has a symmetrical four-point grasp and is built in hard elastic material, increasing the grasping force and responsiveness. There is space inside the lip to handle large workpiece volumes and a highly irregular input. The fingers are solid, enabling them to conform around small objects and rough contours. Twenty fine ripples on the tip of the fingers, secures a grip on smooth surfaces and generates friction on wet ones.

#### . FINGER

1: SOLID

# **CAPABILITIES**

# **APPLICATION**



BELT HANDLING



BIN HANDLING



HARVESTING



**ASSEMBLY** 

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### **WORKPIECE**



DIAMETER

40-110 mm



PAYLOAD

<500 g



SOUARE





CYLINDER





ROUND



ODD SHAPED





RIDGET





**DEFORMABLE** 





SMOOTH



RUGGED



WET



FRAGTILE



STACKABLE

